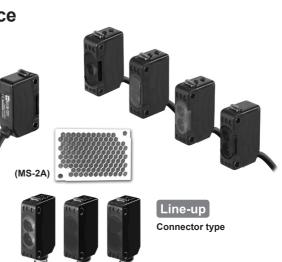
Compact and Long sensing distance

Features

- Long distance sensing type
- Long sensing distance with high quality lens
- Long sensing distance : Through-beam type 15m, Diffuse reflective type 1m,
- Polarized retroreflective type 3m(MS-2A) • M.S.R.(Mirror Surface Rejection) function
- (Polarized retroreflective type)
- Compact size: W20×H32×L10.6mm
- Protection structure IP65/IP67(IEC standard)
- Light ON/Dark ON selectable by VR
- Sensitivity adjustment VR incorporated
- Built-in reverse power polarity, output short, overcurrent protection circuit
- Mutual interference prevention function (Except through-beam type)
- Improved noise resistance and minimize effect of disturbance light
- Please read "Caution for your safety" in operation C F manual before using.

Specifications

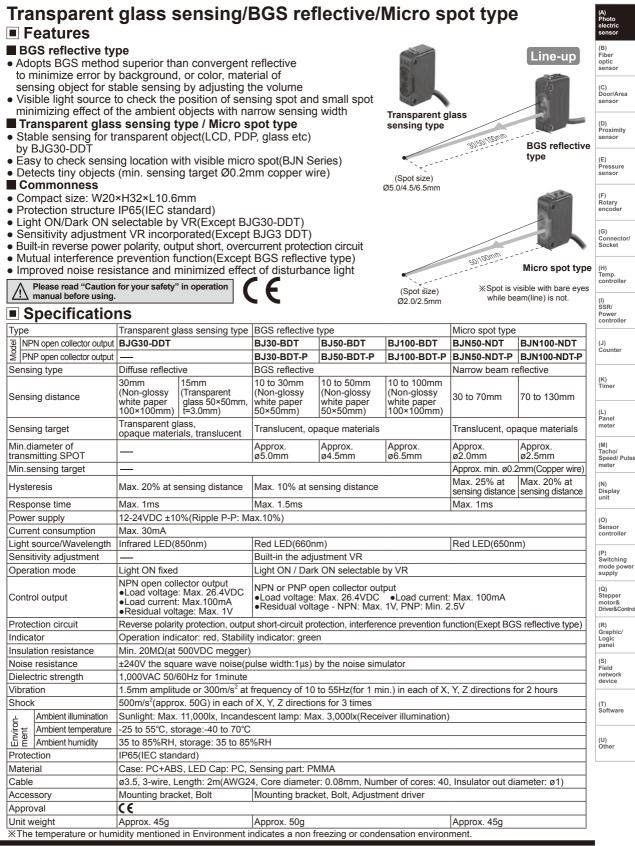


%The model name with '-C' is connector type.

Туре		Long distance s	ensing type						
NPN of collector PNP of	pen pr output	BJ15M-TDT BJ15M-TDT-C	BJ10M-TDT BJ10M-TDT-C	BJ7M-TDT	BJ3M-PDT BJ3M-PDT-C	BJ1M-DDT BJ1M-DDT-C	BJ300-DDT BJ300-DDT-C	BJ100-DDT BJ100-DDT-C	
≥ PNP or collecto	pen proutput	BJ15M-TDT-P BJ15M-TDT-C-P	BJ10M-TDT-P BJ10M-TDT-C-P	BJ7M-TDT-P	BJ3M-PDT-P BJ3M-PDT-C-P	BJ1M-DDT-P BJ1M-DDT-C-P	BJ300-DDT-P BJ300-DDT-C-P	BJ100-DDT-P BJ100-DDT-C-F	
Sensing type		Through-beam			Polarized retroreflective	Diffuse reflective			
Sensing distance		15m	10m	7m	0.1 to 3m ^{×1} (MS-2A)	1m (Non-glossy white paper 300×300mm)	300mm (Non-glossy white paper 100×100mm)	100mm (Non-glossy white paper 100×100mm	
Sensing target		Opaque material over ø12mm Opaque materia over ø8mm			Opaque material over ø75mm	Translucent, opaque materials			
Hysteresis		Max. 20% at sensing distance							
Response	e time	Max. 1ms							
Power su	pply	12-24VDC±10%(Ripple P-P: Max.10%)							
Current co	onsumption	Emitter/Receive	Emitter/Receiver: Max. 20mA Max. 30mA						
Light sou	rce	Infrared LED (850nm)	Red LED (660nm)	Red LED (650nm)	Red LED (660nm)	Infrared LED (850nm)	Red LED (660nm)	Infrared LED (850nm)	
Sensitivity	adjustment	Built-in the adjust	Built-in the adjustment VR						
Operatior	n mode	Light on/Dark or	selectable by V	R					
Control o	utput		en collector outp Max. 26.4VDC ●I		lax. 100mA •Res	idual voltage - N	IPN: Max. 1V, PN	P: Max. 2.5V	
Protection	n circuit	Reverse polarity protection, output short-circuit protection, interference prevention function(Except through-beam type)							
Indicator		Operation: Red, Stable: Green(Emitter's power indicator: Green)							
Insulation resistance		Max.20MΩ(at 500VDC megger)							
Noise resistance		±240V the square wave noise(pulse width:1µs) by the noise simulator							
Dielectric	strength	1000VAC 50/60Hz for 1minute							
Vibration		1.5mm amplitude or 300m/s ² at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours							
Shock		500m/s ² (approx. 50G) in each of X, Y, Z directions for 3 times							
Ambient illumination Ambient temperature Ambient humidity		Sunlight: Max. 11,000lx, Incandescent lamp: Max. 3,000lx(Receiver illumination)							
		-25 to 55°C, storage: -40 to 70°C							
		35 to 85%RH, storage: 35 to 85%RH							
Protection	า	BJ - IP65(IEC standard), BJ-C - IP67(at non-dew status)							
Material		Case: PC+ABS, LED Cap: PC, Sensing part: PMMA							
Cable ^{**2}		BJ: ø3.5, 3-wire, Length: 2m(Emitter of through-beam type: ø3.5, 2-wire, Length: 2m) (AWG24, Core diameter: 0.08mm, Number of cores: 40, Insulator out diameter: ø1)							
A 000000	Common	Mounting bracket, Bolt, Nut, VR adjustment driver							
Accessor	y Individual	Reflector(MS-2A) —							
A		CE							
Approval		BJ: Approx. 90g, BJ-C: Approx. 20g BJ: C: Approx 60g BJ: C: Approx. 45g, BJ-C: Approx. 10g							

%2: M8 connector cable is sold separately. (Cable - AWG22, Core diameter: 0.08mm, Number of cores: 60, Insulator out diameter: Ø1.25) %The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.



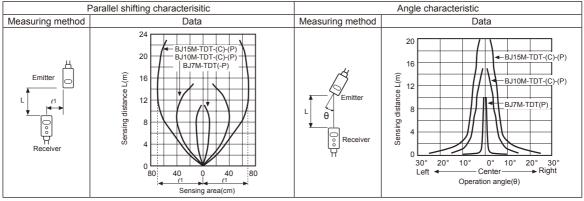


Autonics

Feature data

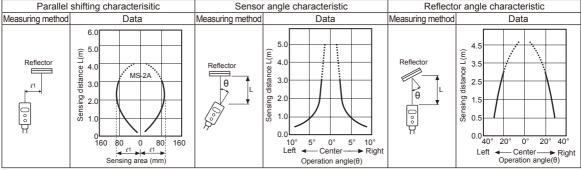
© Through-beam type

BJ15M-TDT-(C)-(P) / BJ10M-TDT-(C)-(P) / BJ7M-TDT-(P)



Retroreflective type

• BJ3M-PDT-(C)-(P)



O Diffuse/Narrow beam reflective type BJ1M-DDT-(C)-(P)

• BJ300-DDT-(C)-(P)

• BJN50-NDT-(P)

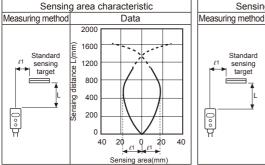
Standard

sensing target

Measuring method

61

0 o o



Sensing area characteristic

30

25

20

15

10

5

0

Sensing distance L(mm

Data

20 15 10 5 0 5 10 15 20

1 1

Sensing area(mm)

1000 (mm) 800 Standard sensina Sensing distance I 600 target 400 200 0⊾ 20 10 0 10 20 Sensing area(mm)

100

80

60

40

20

0

Autonics

2

1

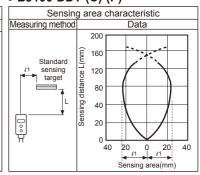
L(mm)

Sensing distance

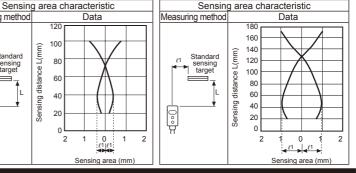
Sensing area characteristic

Data

• BJ100-DDT-(C)-(P)



• BJN100-NDT-(P)



BJG30-DDT

Standard

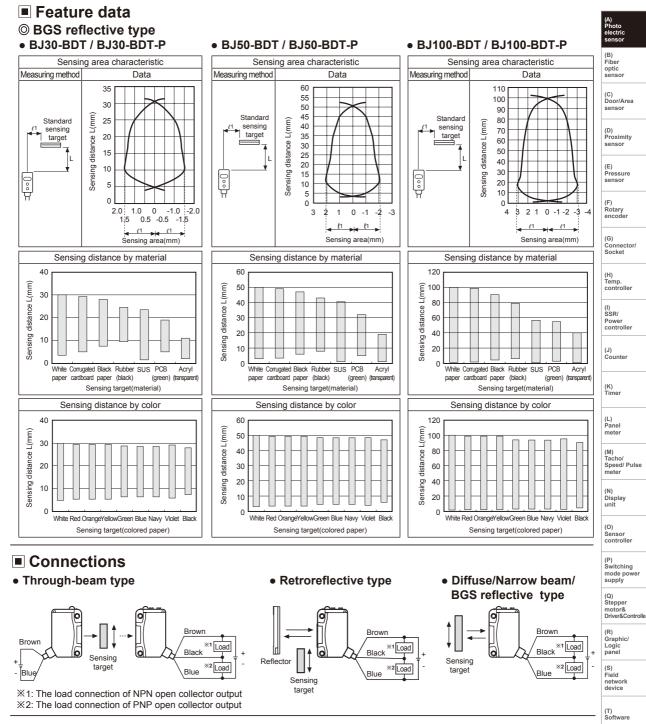
sensing target

Measuring method

01

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Long sensing distance/BGS reflective/Micro spot type



Connections for connector part



Connector pin No.	Cable colors	Function	
1	Brown	Power Source(+V)	
2	White	—	
3	Blue	Power Source(0V)	
4	Black	Output	

Connector cable(sold separately)

Connector cable model

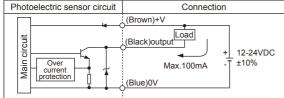
: CID408- 🗌 , CLD408- 🗌

- XPlease refer to G-6 for connector cable.
- Autonics

(U) Other

Control output diagram

NPN open collector output



Operation mode

Operation mode	Light ON	Dark ON		
Receiver operation	Received light	Received light		
Operation indicator (red LED)	ON OFF	ON OFF		
Transistor output	ON OFF	ON OFF		

• PNP open collector output

Photoelectric sensor circuit

Over

current

circuit

Main

Dimensions

m

(unit: mm)

12-24VDC

±10%

Connection

32

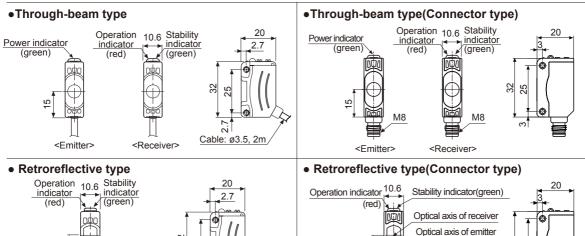
22

Max.100mA

(Brown)+V

(Black)output

(Blue)0V Load



Diffuse/Narrow beam/BGS reflective type Connect the bracket A

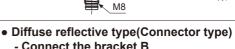
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32

25

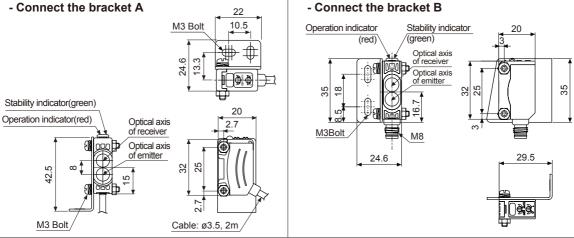
~i

Cable: ø3.5, 2m

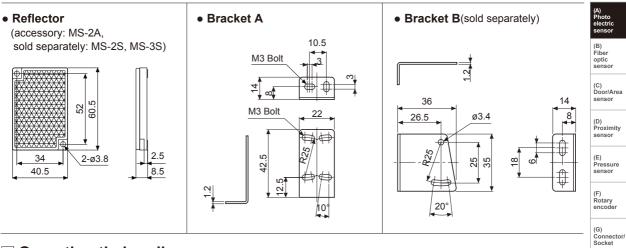


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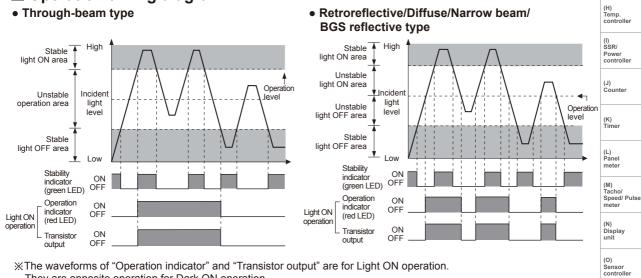


Long sensing distance/BGS reflective/Micro spot type



Operation timing diagram

• Through-beam type

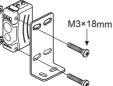


* The waveforms of "Operation indicator" and "Transistor output" are for Light ON operation. They are opposite operation for Dark ON operation.

Mounting and sensitivity adjustment

O For mounting

Please use bolts M3 for mounting of sensor. set the tightening torque under 0.5N·m.



Switching of operation mode

Light ON operation	Turn the switching volume of operation mode to end of right(L direction), it is set as Light ON.
Dark ON operation	Turn the switching volume of operation mode to end of left(D direction), it is set as Dark ON.

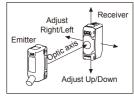
%For through-beam type, the switching volume of operation mode is built-in the receiver.

Optical axis adjustment

Retroreflective/Diffuse/Narrow beam/

•Through-beam type

- 1. Place the emitter and the receiver facing each other and supply the power.
- 2. After adjusting the position of the emitter and the receiver and check their stable indicating range, mount them in the middle of the range.



- 3. After mounting this unit, check the operation of the sensor and lighting of the stability indicator in both status. (None or sensing target status)
- XWhen the sensing target is translucent or small(under sensing target of ' Specifications'), it may not be detected by the sensor because the light can penetrate it.

(P) Switching mode powe supply

(Q) Stepper

motor& Driver&Co

(R) Graphic/

Logic panel

(S) Field network device

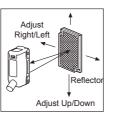
(T) Software

(U) Other

Autonics

• Retroreflective type

- Place the sensor and the reflector facing each other and supply the power.
- After adjusting the position of the sensor and reflector and check their stable indicating range, mount them in the middle of the range. (None or sensing target status)

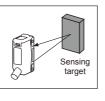


3. After mounting this unit, check the operation of the sensor and in both status. (None or sensing target status)

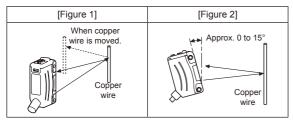
• Diffuse/Narrow beam/BGS reflective type

After place a sensing target, adjust the sensor to up or down, right or left.

Then, fix the sensor in the center of position where the stability is operating.



Object(Copper wire) detection <Micro spot type>

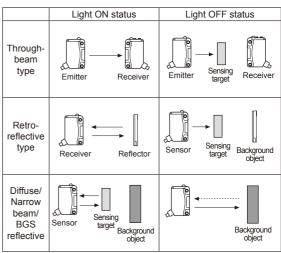


Mount the sensor slanted at an angle ranged 0 to 15° shown above as [Figure 2] for stable detection to detect as shown in [Figure 1].

Sensitivity adjustment

Order	Position	Description		
1	(A) MIN. MAX.	Turn the adjustment VR to the right of min. and check position(A) where the operation indicator is turned ON in "Light ON status".		
2	(A) (C) MIN. MAX. (B)	Tum the adjustment VR more to the right of position(A), check position(B) where the operation indicator is turned ON. And tum the adjustment VR to the left, check position(C) where the operation indicator is turned OFF in "Light OFF status". %If the operation indicator is not turned ON although the adjustment VR is turned to the max. position, the max. position is (C).		
3	Optimal sensitivity (A)	Set the adjustment VR at the center of (A) and (C). To set the optimum sensitivity, check the operation and lighting of stability indicator with sensing target or without it. If the stability indicator is not turned ON, please check the sensing method again because sensitivity is unstable.		

%No sensitivity adjustment function available for BJG30-DDT models.



- Set the sensitivity to operate in stable light ON area and the reliability for the environment (temperature, voltage, dust etc) is increased. In unstable light ON area, be sure that the variation of environment.
- **Do not apply excessive force on the adjustment VR, it may be broken.